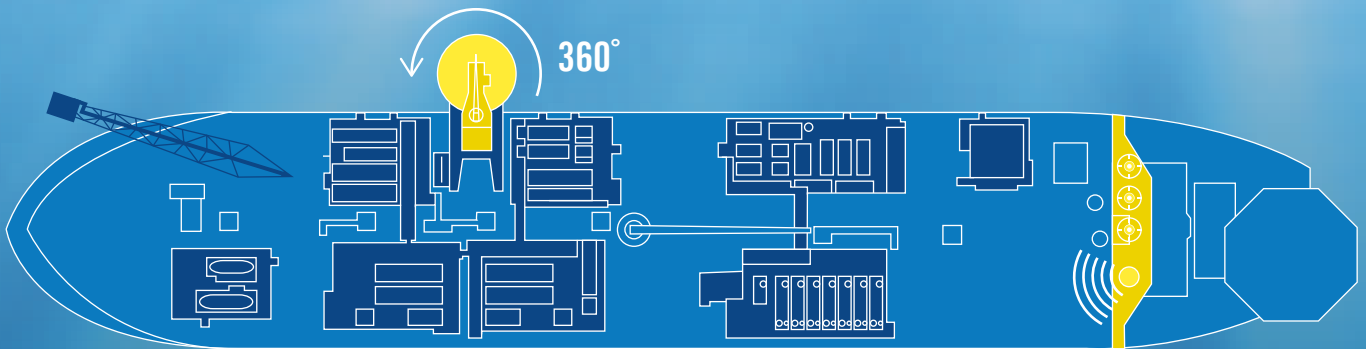


Dynamic Positioning (DP2) System

A DP2 system allows the Modular Capture Vessels (MCVs) to maintain a fixed position despite external forces, such as wind, waves and current.



360° rotation of MCV around Riser Turret Module (RTM)

1 satellite-based global positioning system

3 wind sensors, motion reference units and gyrocompasses to detect positioning deviations



4 azimuth thrusters to steer and move the MCV from side to side



1 bow tunnel thruster to steer the MCV



1 engine with Controllable Pitch Propeller to navigate the MCV forward and backward